

ICS 25.040.30

CCS J 28



**NATIONAL STANDARD OF THE
PEOPLE'S REPUBLIC OF CHINA**

GB/T 19400-2003

**Industrial robots -- Object handling with grasp-type grippers-
Vocabulary and presentation of characteristics**

(English Translation)

Issued on: November 20, 2003

Implemented on: May 1, 2004

**Issued by: General Administration of Quality Supervision, Inspection and
Quarantine of the People Republic of China**

Table of Contents

What this standard covers	1
Document data	2

What this standard covers

This standard specifies: a grip -type grippers Object handling Terminology and grip -type holder function, structure and component Terminology. This standard focus is on the end of the actuator defined functions and 4. 1. 2. 1 grip -type holder. Information Appendix A also gives the holder grip type of characteristics format. This form applies to the following situations: a, of end users of the robot manufacturers provide their product characteristics. b, robot user that they need end effectors requirements. c) description of the robot user is moving objects as well as the characteristics of a given robotic applications in the handling of objects properties. This standard also applies to industrial robots are not involved simple operation, such as

Document data

International classification (ICS): 25.040.30.

Chinese classification (CCS): J28.

Estimated length of the Chinese original: 26,230 words.

Adopted international standard: ISO 14539-2000; IDT.